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### (54) Decoding instructions

(57) A decode unit (20) decodes instructions in a processor. These instructions include instructions of a first length in a first instruction mode and instructions of a second, shorter length in a second instruction mode. The decode unit has decoding circuitry (50-60) which decode the instructions. A register holds the instruction mode and generates an instruction mode signal. Switching circuitry (MUX6, MUX7) is responsive to the instruction mode signal to output decoded instructions from the

decode unit depending on the instruction mode. A detector (70) is provided for detecting a length change instruction of the second, shorter length while in the second instruction mode which indicates that the subsequent instruction is of the first length. The detector also temporarily alters the state of the instruction mode signal to allow the first length instructions to be decoded without changing the instruction mode held in the register.

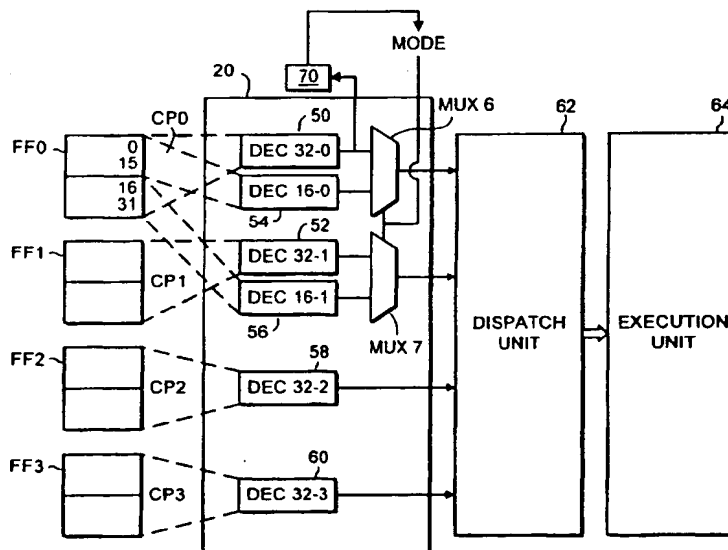


FIG. 5

## Description

**[0001]** The present invention relates to decoding instructions in a computer system such as a processor.

**[0002]** In a computer system, instructions are typically fetched from a program memory, decoded and supplied to an execution unit where they are executed to run the program stored in the program memory. It is advantageous for such a computer system to be able to support more than one instruction mode. A novel computer system described herein can support three instruction modes.

**[0003]** According to a first instruction mode, during each machine cycle two 32 bit instructions are decoded, referred to herein as GP32 mode.

**[0004]** According to a second instruction mode, during each machine cycle a pair of 16 bit instructions are decoded, referred to herein as GP16 mode.

**[0005]** According to a third instruction mode, four 32 bit instructions are decoded during each machine cycle, referred to herein as VLIW mode.

**[0006]** In practice, a prefetch unit fetches a word from memory having a length of 128 bits. This word can contain eight 16 bit instructions (GP16 mode), four independent 32 bit instructions (GP32) or four interrelated 32 bit instructions (VLIW mode). The four 32 bit instructions in VLIW mode are interrelated in the sense that they have to conform to a certain grammar such that they can be fetched and supplied to the decoder together. The prefetch unit supplies an 128 bit sequence to the decode unit on each machine cycle. However, the decode units should supply to the execution unit decoded outputs only for the instructions to be decoded in that machine cycle, which depends on the instruction mode.

**[0007]** In the second instruction mode, the nature of the 16 bit instructions can sometimes limit the manipulations to be carried out by the execution unit. It is therefore advantageous to allow a 32 bit instruction to be included in a sequence of instructions in GP16 mode. If this is done however then it would be necessary to include an instruction to alter the instruction mode of the computer system each time prior to execution of a 32 bit instruction and then to have an additional instruction to change the mode back again to continue to decode and execute 16 bit instructions.

**[0008]** According to the present invention in one aspect there is provided a decode unit for decoding instructions in a processor including instructions of a first length in a first instruction mode and instructions of a second, shorter length in a second instruction mode, the decode unit including: decoding circuitry for decoding instructions; a register for holding the instruction mode and generating an instruction mode signal; switching circuitry responsive to the instruction mode signal to output decoded instructions from the decode unit depending on the instruction mode; and means for detecting a length change instruction of the second, shorter length while in the second instruction mode which indicates

that the subsequent instruction is of the first length and for temporarily altering the state of the instruction mode signal to allow the first length instructions to be decoded without changing the instruction mode held in the register.

**[0009]** In another aspect the present invention provides a processor comprising: at least one execution unit for executing instructions; an instruction mode indicator which indicates one of a plurality of instruction modes for the processor; a decode unit for decoding instructions prior to dispatch to the at least one execution unit; and an instruction supply mechanism for supplying instructions to the decode unit, wherein said instructions are represented by bit sequences the length of which depends on an instruction mode of the processor, and wherein the decode unit comprises: decoding circuitry for decoding the instruction; switching circuitry responsive to an instruction mode signal generated by the instruction mode indicator to output decoded instructions from the decode unit depending on the instruction mode; means for detecting a length change instruction of a second length while in a second instruction mode which indicates that the subsequent instruction is of a first length and for temporarily altering the state of the instruction mode signal to allow the first length instruction to be decoded without changing the instruction mode held at the instruction mode indicator.

**[0010]** In a further aspect, the invention provides a method of decoding instructions in a processor, the instructions each being of a predetermined length and including a length change instruction which indicates that a subsequent instruction is of a different length, the method comprising: detecting the length change instruction in a decode unit; temporarily altering the outputs of the decode unit to permit the different length instruction to be decoded; and after the different length instruction has been decoded, defaulting to decoding of the instructions of the predetermined length.

**[0011]** The length change instruction is named herein as Gp32nxt. It thus allows a 32 bit instruction to be decoded and executed while the machine remains in GP16 mode. This gives GP16 mode a greater flexibility than it would have if all instructions were restricted to the 16 bit length. Moreover, it overcomes the need to change the mode of the computer system just to execute a single 32 bit instruction in an instruction sequence of 16 bit instructions.

**[0012]** It will be appreciated that the length change instruction and the following 32 bit instruction needs to be atomic, i.e. executable without any interrupts. This is because once the decoder has detected the length change instruction, the next output from the decoder will be as though a 32 bit instruction has been decoded.

**[0013]** The decode circuitry comprises in the preferred embodiment a first decoder having an input connected to receive a bit sequence of the first length and operating on receipt of said bit sequence to generate a first decoded output; a second decoder having an input

connected to receive a bit sequence of the second length and operating on receipt of said bit sequence to generate a second decoded output; and a communication path for supplying a bit sequence simultaneously to said first and second decoders.

**[0014]** Thus, as described in the following, in order to manage different instruction modes, the decode unit has a plurality of dedicated decoders each of which receives and decodes the bit sequence during each machine cycle. Depending on the instruction mode of the machine, the outputs of selected one of the decoders are supplied to the execution unit for execution. The outputs of the other decoder are not required and thus are not selected.

**[0015]** For a better understanding of the present invention and to show how the same may be carried into effect reference will now be made by way of example to the accompanying drawings in which:-

Figure 1 is a block diagram of a prefetch unit;  
Figure 2 illustrates the different instruction modes of the processor;  
Figure 3 illustrates the organisation of a prefetch buffer;  
Figure 4 is a circuit diagram illustrating the key components of the prefetch buffer; and  
Figure 5 is a block diagram of a decode unit.

**[0016]** Figure 1 is a block diagram of a prefetch unit 2 for a processor, the prefetch unit 2 comprising a prefetch buffer 4 with associated control bits 6 and control circuitry comprising a prefetcher 8 and an aligner 10. The prefetcher 8 is connected to a program memory 12 and is responsible for initiating memory accesses to the program memory 12 using memory access control signals 14a, 14b. The address in memory to which a fetch is initiated is held in a prefetch program counter 16 in the prefetcher 8. Control of the prefetch program counter is not discussed herein, but it can be assumed that fetches are initiated from memory in accordance with a sequence of instructions to be executed by the processor. That is, the prefetch program counter may be incremented each time as a sequence of adjacent instructions is fetched, or it may change according to branches, traps, interrupts etc. Responsive to a memory fetch initiated by the prefetcher, instruction words are supplied from the program memory 12 to the prefetch buffer 4 as represented by data-in path 18.

**[0017]** The aligner 10 controls reading of instructions from the prefetch buffer to a decode unit 20 along data-out path 22. To do this, the aligner issues and is responsive to prefetcher align (PFAL)/decoder control signals 24a, 24b. The aligner 10 has an align program counter 26 which keeps track of how many instructions have been dispatched to the decoder 20 in each machine cycle, and a state machine 28 which generates a read pointer RP for controlling the prefetch buffer in a manner which is described in more detail hereinafter.

**[0018]** Instructions in the program memory 12 can have a length of 16 bits or 32 bits. The prefetch buffer supports three different instruction modes as described with reference to Figure 2 as follows. The instruction mode is held in a process status register (PSR) 3 at the decode unit 20 and can be changed. The change of instruction mode can be caused for example by specific change mode instructions which set the PSR accordingly. Change mode signals chmd1, chmd2 are issued by the decoder 20 responsive to a change in instruction mode.

**[0019]** According to a first instruction mode, two instructions each having a length of 32 bits are supplied to the decoder from the prefetch buffer in each machine cycle, for example w0, w1 in CYCLE 0. This mode is referred to herein as GP32 mode.

**[0020]** According to a second instruction mode, a pair of 16 bit instructions are supplied during each machine cycle to the decoder 20 from the prefetch buffer 4. This pair is denoted slot0, slot1 in bit sequences w0, w1 etc. This is referred to herein as GP16 mode.

**[0021]** According to a third instruction mode, four instructions w0, w1, w2, w3 each of 32 bits in length are supplied to the decoder in each machine cycle. This is referred to herein as VLIW. In VLIW mode the instructions in each instruction word (128 bits) conform to certain grammatical rules.

**[0022]** In all modes, each fetch operation initiated to the program memory 12 retrieves an instruction word of 128 bits in length. Thus, in GP16 mode, the instruction word comprises eight 16 bit instructions, paired as slot0, slot1 for each machine cycle. In GP32 and VLIW mode, the instruction word comprises four 32 bit instructions.

**[0023]** The organisation of the prefetch buffer 4 is illustrated in Figure 3. In diagrammatic terms, the prefetch buffer can be considered to have four successive lines L0 to L3, each having a capacity of 128 bits. There is a single write port WPO having a width of 128 bits which receives data from the program memory via the data-in path 18 and an input latch FF-in and writes it into the selected line under the control of a write pointer WP [3:0]. Each line comprises four storage locations each having a capacity of 32 bits and each of which is shown diagrammatically divided into two 16 bit sections for the purposes of explanation. The storage locations are denoted F0 to F15. Each line in Figure 3 is referred to herein as a group of storage locations and has the capacity for one 128 bit line from memory. This allows up to four successive memory accesses to be made, even if the first instruction word has not been received or executed by the processor. While the instruction word in storage locations F0 to F3 is being decoded and subsequently executed, memory fetches can continue to be implemented into the storage locations F4 to F7, F8 to F11 and F12 to F15 until the buffer is full. By the time that a memory fetch has been made into the last group F12 to F15, it is most likely that the first group F0 to F3

will have been completely read out into the decode unit and will thus be ready to receive a subsequent instruction word from memory. The number of cycles required to decode an instruction word in each group varies depending on the instruction mode of the machine in a manner which will be described in more detail in the following. Nevertheless, a minimum of one cycle is required for reading and decoding, and therefore the use of the prefetch buffer hides memory latency.

**[0024]** In order to save a cycle when the prefetch buffer is empty or flushed after a branch, data can bypass the prefetch buffer through a bypass circuitry BS. As described in more detail later, the bypass circuitry is implemented as a plurality of multiplexors (MUX0 to MUX3 in Figure 4).

**[0025]** Figure 4 is a more detailed diagram of the prefetch buffer and its associated read circuitry. The storage locations F0 to F15 are illustrated aligned vertically for the purposes of explanation.

**[0026]** The control bits 6 described above in Figure 1 include empty flags EF1 to EF4 which indicate when a complete 128 bit line of storage locations is empty such that a subsequent memory fetch can be initiated. When a fetch is instituted from memory, and data has been received by the prefetch buffer, the empty flag is cleared to indicate that those storage locations are now full.

**[0027]** Reading from the prefetch buffer will now be described with reference to the schematic diagram of Figure 4. The prefetch buffer includes four read ports RP1, RP2, RP3 and RP4. These read ports each take the form of multiplexors each capable of connecting selected ones of the storage locations F0 to F15 to a 32 bit output, pf-buf-out1, 2, 3 or 4. However, the read ports are not identical. The first read port RP1 has sixteen inputs each of which is connected to a respective storage location F0 to F15 and each of which can be connected to the output pf-buf-out1. The second read port RP2 has eight inputs which are respectively connected to storage locations F1, F3, F5, F7, F9, F11, F13, F15 to selectively connect the contents of those storage locations to the output pf-buf-out2.

**[0028]** The third read port RP3 has four inputs connected to storage locations F2, F6, F10 and F14 for selectively connecting the contents of those storage locations to the output pf-buf-out3. The fourth read port RP4 also has four inputs which are connected to storage locations F3, F7, F11 and F15 for selectively connecting the contents of those storage locations to the output pf-buf-out4.

**[0029]** The read ports RP1 to RP4 are controlled by the read pointer RP from the aligner 10 in dependence on the instruction mode of the machine and the consequential number of machine cycles required for decoding each instruction word.

**[0030]** Alternatively, for instructions supplied directly from memory along data-in path 18, the control of instructions supplied to the decoder in dependence on the instruction mode and machine cycles is additionally con-

trollable by multiplexors MUX0, MUX1, MUX2 and MUX3. These receive at their input respective bits of the 128 bit data-in path 18 to supply a 32 bit sequence to each multiplexor in each machine cycle as described in the following.

**[0031]** The selection of which instructions within the instruction word are supplied to the decode unit 20 is made on dependence on the instruction mode as described in the following. In Figure 3, the symbols w0 to w3 are used on different input lines of the multiplexors MUX0 to MUX3 to represent different 32 bit sequences, as in Figure 4. The definition of each 32 bit sequence depends on the instruction mode, but bits of the data-in path are always allocated as w0 [0:31], w1 [32:63], w2 [64:95], w3 [96:127]. The inputs to the multiplexors are individually labelled so as to distinguish between them. That is, in GP16 mode, on the first decode cycle, cycle 0, the first sequence w0 is supplied to the decoder 20. This presents a pair of 16 bit instructions, slot0, slot1 (w0) for simultaneous decoding by the decode unit 20. On the next cycle, cycle 1, the sequence w1 is supplied, presenting the next pair of 16 bit instructions slot0, slot1 (w1) for decoding. In GP16 mode, the read port RP1 and the multiplexor MUX0 are the only read devices which are used and the control of the word which is supplied to the decode unit is made by the multiplexor MUX0 under the control of signal mux-ctrl10, and the read pointer RP. If the signal mux-ctrl10 selects the read port output pf-buf-out1, the read pointer selects inputs F0 to F3 over four successive cycles CYCLE0 to CYCLE3 to read out successively w0 to w4. Once storage location F3 has been read out, the read port counter will reset the read port RP1 so that it reads out from storage locations F4 to F7 over the next four cycles. If the buffer is not in use, the first instruction pair w0 is read out by the multiplexor MUX0. That is in cycle 0, input M00 of the multiplexor MUX0 is selected. Meanwhile, the 128 bit line is loaded into the first location of the prefetch buffer and the read pointer points to the next location to be read out by the decode unit. Therefore on cycle 1, the next instruction pair w1 is read out by the multiplexor MUX0 by selecting pf-buf-out1

**[0032]** In GP32 mode, in the first machine cycle the first two instructions w0, w1 are presented to the decode unit 20. In the subsequent cycle, cycle 1, the next two instructions w2, w3 are presented to the decode unit. This utilises read ports RP1 and RP2 and the multiplexors MUX0 and MUX1. If the signal mux-ctrl10 is set to pf-buf-out1, and mux-ctrl11 to pf-buf-out2, then the read pointer RP is set to F0 for RP1 and F1 for RP2 in cycle 0. In cycle 1, it is changed to F2 and F3 respectively. Instructions are then read over the next two cycles from the next group of storage locations F4 to F7 by altering the setting of the read ports RP1 and RP2 responsive to the read pointer RP. Alternatively, when read from the data-in path 18, in the first cycle, the first input M10 of the multiplexor MUX1 is set to read w1 (bits 31 to 63) and the first input M00 of the multiplexor MUX0 is set to

read w0 (bits 0 to 31). Thus, instructions w0 and w1 are presented to the decode unit 20 in CYCLE 0. Meanwhile, the 128 bit line is loaded into the prefetch buffer so that in the subsequent cycle, CYCLE 1, w2 and w3 are read from the buffer by selecting pf-buf-out1 and pf-buf-out2.

**[0033]** In VLIW mode, four 32 bit instructions W0 to W3 (slot0 to slot3) are supplied simultaneously to the decode unit 20 in each machine cycle, e.g. CYCLE 0. The multiplexors MUX2 and MUX3 are set according to the control signals mux-ctrl2 and mux-ctrl3 respectively to allow the instruction words w2 and w3 to be read either from the buffer or from the data-in path 18. In other respects, the settings of RP1 and RP2, MUX0 and MUX1 are as in GP32 mode. However, in the subsequent cycle, e.g. CYCLE 1 in VLIW mode, it will be noticed that the instruction words w2 and w3 which would have been remaining in GP32 mode have now been read out. Therefore, the read pointer RP can immediately move on to the next set of storage locations F4 to F7 to read out the subsequent VLIW instruction word containing the next four instructions.

**[0034]** Data is passed from the multiplexors MUX0 to MUX3 to respective output flip-flops FF0 to FF3 via a set of control gates labelled GC1, GC2 and GS0 to GS3. The control gates GC1, GC2 are responsive to change mode signals chmd1, chmd2 respectively which indicate to the prefetch unit that there has been a change in the instruction mode in which the machine is operating. The control gates GS0 to GS3 are responsive to respective stop signals stop[0] to stop[3] to prevent any new data from entering the decode unit from that output flip-flop. These effectively allow the decode unit to be stalled. In a stop condition, the outputs of the flip-flops are recirculated to the input of its associated control switch to prevent unnecessary operation of the subsequent decoder.

**[0035]** Operation of the prefetch unit responsive to the change mode signals chmd1 and chmd2 will now be described. The output flip-flop FF0 is connected to a single 32 bit decoder and to two 16 bit decoders. When the machine is in GP16 mode, the outputs of the two 16 bit decoders are selected for the instruction pair supplied to the flip-flop FF0. When the machine is in GP32 mode, the output of the 32 bit decoder is selected. The remaining flip-flops FF1 to FF3 are each connected to respective 32 bit decoders.

**[0036]** A first change mode signal chmd1 signals a change of machine instruction mode from GP32 to GP16. If the machine had been operating in GP32 mode, consider the situation at the end of cycle 0 which reference to Figure 2. Instructions w0 and w1 will have been supplied via the flip-flops FF0 and FF1 to the respective 32 bit decoders of the decoder 20. However, the change in instruction mode now implies that the 32 bit sequence which was formerly to be considered as the second instruction W1 in cycle 0 of GP32 mode, in fact contains a pair of 16 bit instructions as denoted in cycle 1 of GP16 mode. Thus, the output of the 32 bit

decoder connected to the flip-flop FF1 needs to be ignored, and the 32 bit sequence w1 needs to be reapplied to the two 16 bit decoders connected to the output flip-flop FF0. This is achieved by the recirculation line 42 from the output of the flip-flop FF1 to the input of the control gate CG1.

**[0037]** Conversely, control signal chmd2 denotes a change of instruction mode from GP16 to GP32. Consider again the effect at the end of cycle 0 with reference to Figure 2. The instruction pair denoted w0 has just been decoded in GP16 mode, and the expectation is that the machine will now wait for the next instruction pair w1. However, in GP32 mode, that word w1 represents a single instruction and the change mode signal chmd2 allows it to be applied directly through the control gate GC2 to the output flip-flop FF1 so that it can be applied directly to the input of the dedicated 32 bit decoder connected to the output of the flip-flop FF1. This allows the instruction w1 to be decoded as a single 32 bit instruction. In the next cycle, instructions w2 and w3 can be transmitted normally as indicated by cycle 1 in GP32 mode in Figure 2.

**[0038]** It will be clear from the above that the number of cycles needed to read all four storage locations in a group depends on the instruction mode. That is; in GP16 mode, four cycles are needed, in GP32 two cycles are needed and VLIW one cycle is needed. When all the storage locations F0 to F3 in the first group have been read, the first empty flag EF1 is cleared to empty.

**[0039]** The aligner controls the setting and clearing of the "empty" flags using information from the read pointer. The aligner detects when the read pointer goes from one line (128 bits) to the next. When this occurs, the "empty" flag corresponding to the page which has just been read is set.

**[0040]** The state of an empty flag being cleared is detected by the prefetcher 8 along line 48 and a fetch is initiated to the next prefetch address in the prefetch program counter 16. Thus, the next instruction line is fetched from memory and the write pointer WP is set to write it into storage locations F0 to F3. In the meantime, the read pointer has moved to the second group F4 to F7 to read and decode instructions of that group. When those storage locations are empty, the empty flag EF2 is cleared, a next memory fetch is initiated by the prefetcher 8 and the read pointer moves onto the group F8 to F11. As can readily be seen, the prefetch buffers masks a latency of memory fetches of at least three cycles in the VLIW mode, and a greater number of cycles in GP32 and GP16 mode. Signals are supplied from the decoder along line 24b to the aligner 10 indicating what mode the decoder is operating in so that the aligner can adjust the align program counter 26 accordingly and keep track of the next instructions to be decoded so that the read pointer RP can correctly be issued by the state machine 28. The control signals 24b sent from the decode unit 20 to the aligner include an acknowledge bit which controls the aligner, in particular the program

counter 26.

[0041] Figure 5 illustrates the details of the decode unit 20. The decode unit comprises six decoders 50, 52, 54, 56, 58 and 60. Four of the decoders 50, 54, 58 and 60 are 32 bit decoders which are labelled DEC32-0, 1, 2 and 3 respectively because they are each associated with the output devices FF0 to FF3 of the prefetch buffer illustrated in Figure 4. There are two 16 bit decoders 52, 56 which are labelled DEC16-0, 1 respectively. Both of the 16 bit decoders 52, 56 are associated with the first output device FF0. The 32 bit decoders 50, 54, 58 and 60 are hard-wired by 32 bit communication paths respectively to the output devices F0 to F3. These communication paths are denoted by the dotted lines CP0 to CP3 in Figure 6. The first 16 bit decoder 52 is hard-wired to the 16 least significant bits of the output of the output device FF0, and the second 16 bit decoder 56 is hard-wired to the 16 most significant bits of the output of the output device FF0. Thus, the bits of each instruction are supplied as a parallel sequence to the decoders.

[0042] The outputs of the top two decoders 50 and 56 are supplied to a first decode multiplexor MUX6 which has an output connected to an instruction dispatch unit 62. The outputs of the second two decoders 54, 56 are connected to a second decode multiplexor MUX7, the output of which is also connected to a dispatch unit 62. The outputs of the lower most decoders 58, 60 are connected directly to the dispatch unit 62. The decoders 50 to 60 are always "on". That is, on each machine cycle they receive the bits on the connection paths CP input to the decoders, perform a decode operation and supply an output. It can readily be seen therefore that of the top four decoders, the outputs of only two of them in each case are of interest. For example, in GP32 mode, it is the outputs of the decoders 50, 54 which are required - the outputs of the decoders 52, 56 being redundant. A mode signal MODE supplied to the multiplexors MUX6, MUX7 selects the appropriate outputs in dependence on the instruction mode of the machine.

[0043] Although the decoders are normally "on", they are responsive only to change in state of the bits supplied to them from the output devices FF0 to FF3. If between two machine cycles, there is no change in state in the outputs of the output devices, then the connected decoder will not need to change any of its internal state. Thus, no power will be consumed by that decoder for as long as the outputs of the output device FF0 to FF3 connected to it do not change. Therefore, by recirculating the outputs using the control switches GS0 to GS3 responsive to the stop signals stop[0] to stop[3] when the relevant decoders are not required, a power saving feature is introduced.

[0044] It is sometimes useful to be able to use a 32 bit instruction in GP16 mode because the instructions in GP16 mode are more limited, while those in GP32 mode allow more complicated operations. Therefore the present system in GP16 mode allows an instruction se-

quence:

- (i) Gp32nxt
- (ii) Instr (32 b)

where (i) is the name of a specific instruction and (ii) represents any 32 bit instruction. Instruction (i) has the effect of allowing execution of eight of the 32 bit instructions while remaining in GP16 mode. The instruction (i) is detected in the decoder and causes the following changes in operation.

[0045] The decoder recognises a Gp32nxt instruction in the detector 70 and causes a MODE signal to switch MUX6 to supply the output of the 32 bit decoder 50 on the next cycle. The decoder acknowledges the subsequent 32 bit instruction to the aligner as two 16 bit instructions. On the subsequent cycle, the MODE signal to MUX6 reverts back to select the output of the 16 bit decoder 52 for decoding of subsequent 16 bit instructions. There is no change in the process status register PSR of the machine. The Gp32nxt instruction avoids the need for wasteful execution of change mode instructions just to execute a single 32 bit instruction while in GP16 mode. It will be appreciated that the sequences (i), (ii) above must however be atomic.

#### Claims

1. A decode unit for decoding instructions in a processor including instructions of a first length in a first instruction mode and instructions of a second, shorter length in a second instruction mode, the decode unit including:

decoding circuitry for decoding instructions;  
a register for holding the instruction mode and generating an instruction mode signal;  
switching circuitry responsive to the instruction mode signal to output decoded instructions from the decode unit depending on the instruction mode; and  
means for detecting a length change instruction of the second, shorter length while in the second instruction mode which indicates that the subsequent instruction is of the first length and for temporarily altering the state of the instruction mode signal to allow the first length instructions to be decoded without changing the instruction mode held in the register.

2. A decode unit according to claim 1, wherein the decoding circuitry comprises:

a first decoder having an input connected to receive a bit sequence of the first length and operating on receipt of said bit sequence to generate a first decoded output;

a second decoder having an input connected to receive a bit sequence of the second length and operating on receipt of said bit sequence to generate a second decoded output; and a communication path for supplying a bit sequence simultaneously to said first and second decoders.

3. A decode unit according to claim 2, which comprises a third decoder having an input connected to receive a bit sequence of the second length and operating on receipt of said bit sequence to generate a third decoded output, wherein the second length is half the first predetermined length.
4. A decode unit according to claim 3, which comprises an input buffer for holding a bit sequence of the first length and simultaneously supplying said bit sequence to the first decoder and to each of the second and third decoders.
5. A decode unit according to any preceding claim, wherein in accordance with the first instruction mode, two instructions each having a length of  $2n$  bits are simultaneously decoded in a machine cycle.
6. A decode unit according to any preceding claim, wherein according to the second instruction mode, each bit sequence has  $2n$  bits and comprises two instructions each of bit length  $n$  which are decoded in a machine cycle.
7. A decode unit according to claim 5 or 6, wherein  $n$  equals 16.
8. A decode unit according to any preceding claim, wherein the switching circuitry comprises a multiplexor.
9. A processor comprising:
  - at least one execution unit for executing instructions;
  - an instruction mode indicator which indicates one of a plurality of instruction modes for the processor;
  - a decode unit for decoding instructions prior to dispatch to the at least one execution unit; and
  - an instruction supply mechanism for supplying instructions to the decode unit, wherein said instructions are represented by bit sequences the length of which depends on an instruction mode of the processor, and
  - wherein the decode unit comprises:
    - decoding circuitry for decoding the instruction;
    - switching circuitry responsive to an instruction mode signal generated by the instruction mode

indicator to output decoded instructions from the decode unit depending on the instruction mode;

means for detecting a length change instruction of a second length while in a second instruction mode which indicates that the subsequent instruction is of a first length and for temporarily altering the state of the instruction mode signal to allow the first length instruction to be decoded without changing the instruction mode held at the instruction mode indicator.

10. A method of decoding instructions in a processor, the instructions each being of a predetermined length and including a length change instruction which indicates that a subsequent instruction is of a different length, the method comprising:

- detecting the length change instruction in a decode unit;
- temporarily altering the outputs of the decode unit to permit the different length instruction to be decoded; and
- after the different length instruction has been decoded, defaulting to decoding of the instructions of the predetermined length.

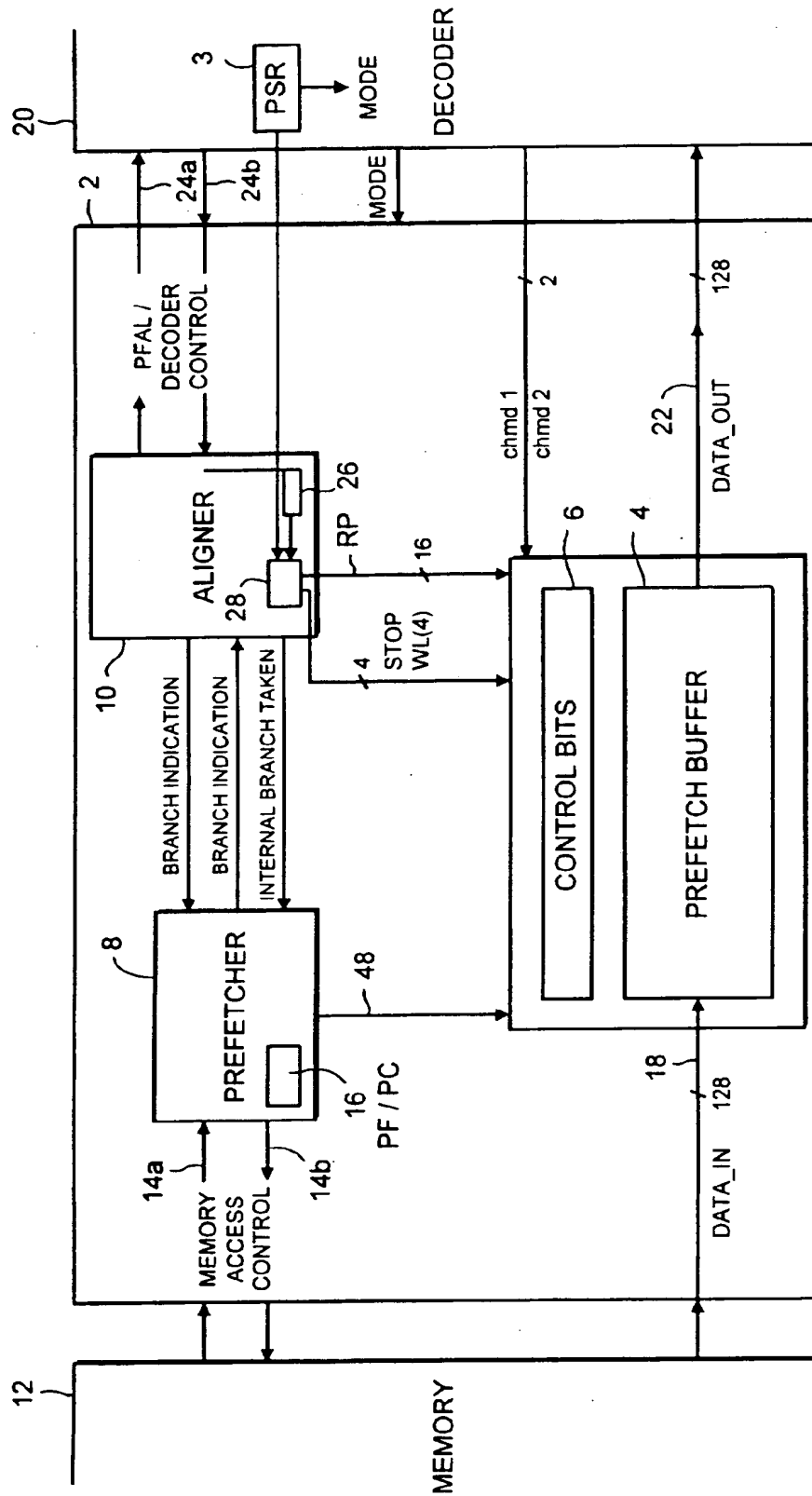


FIG. 1



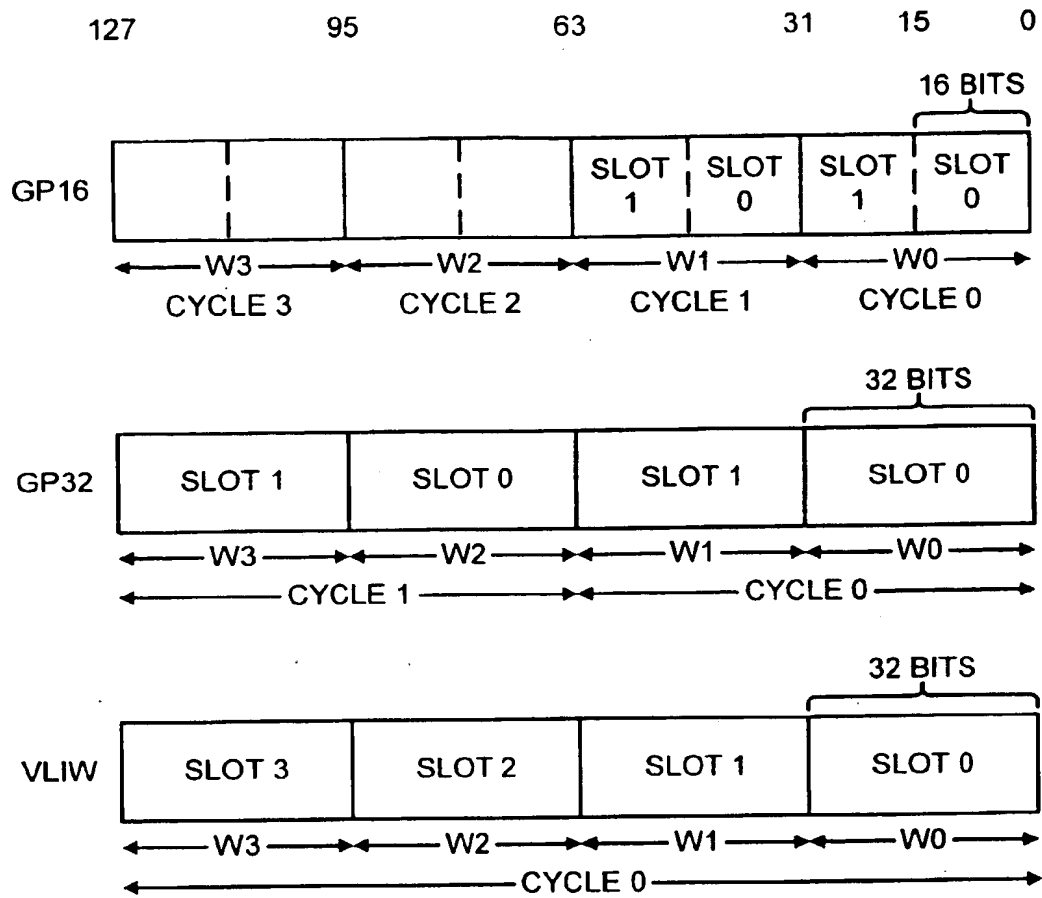


FIG. 2

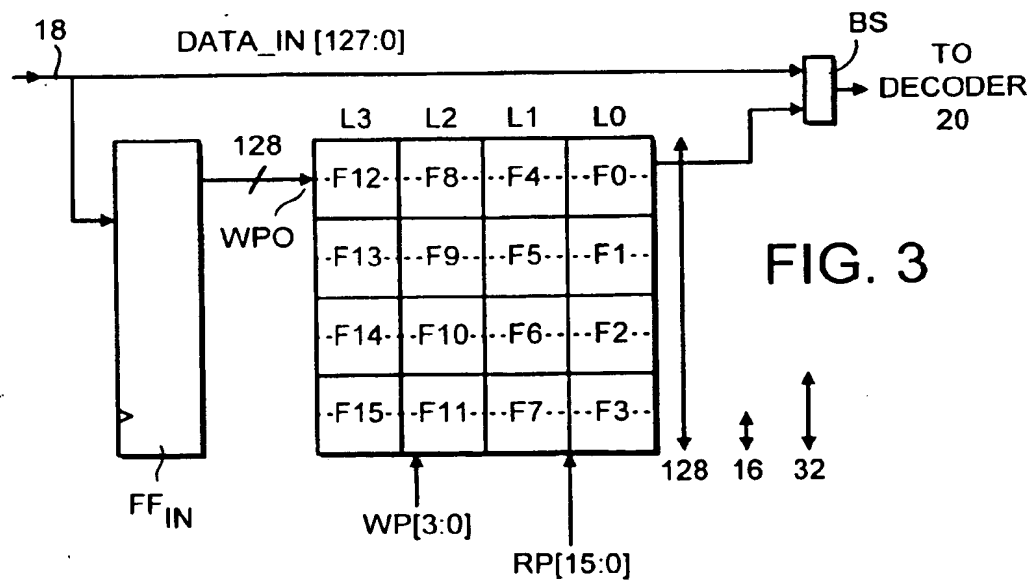


FIG. 3

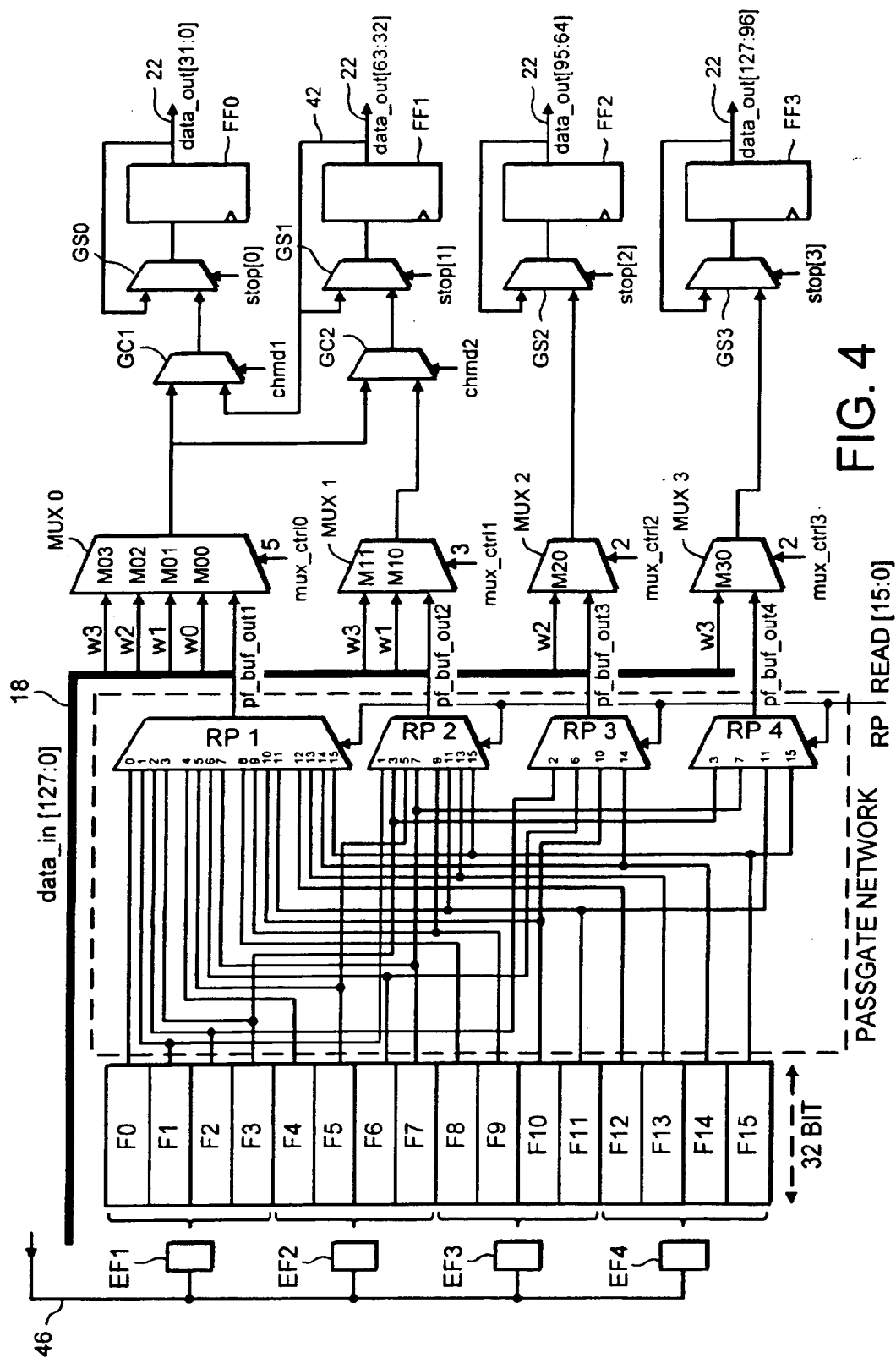


FIG. 4

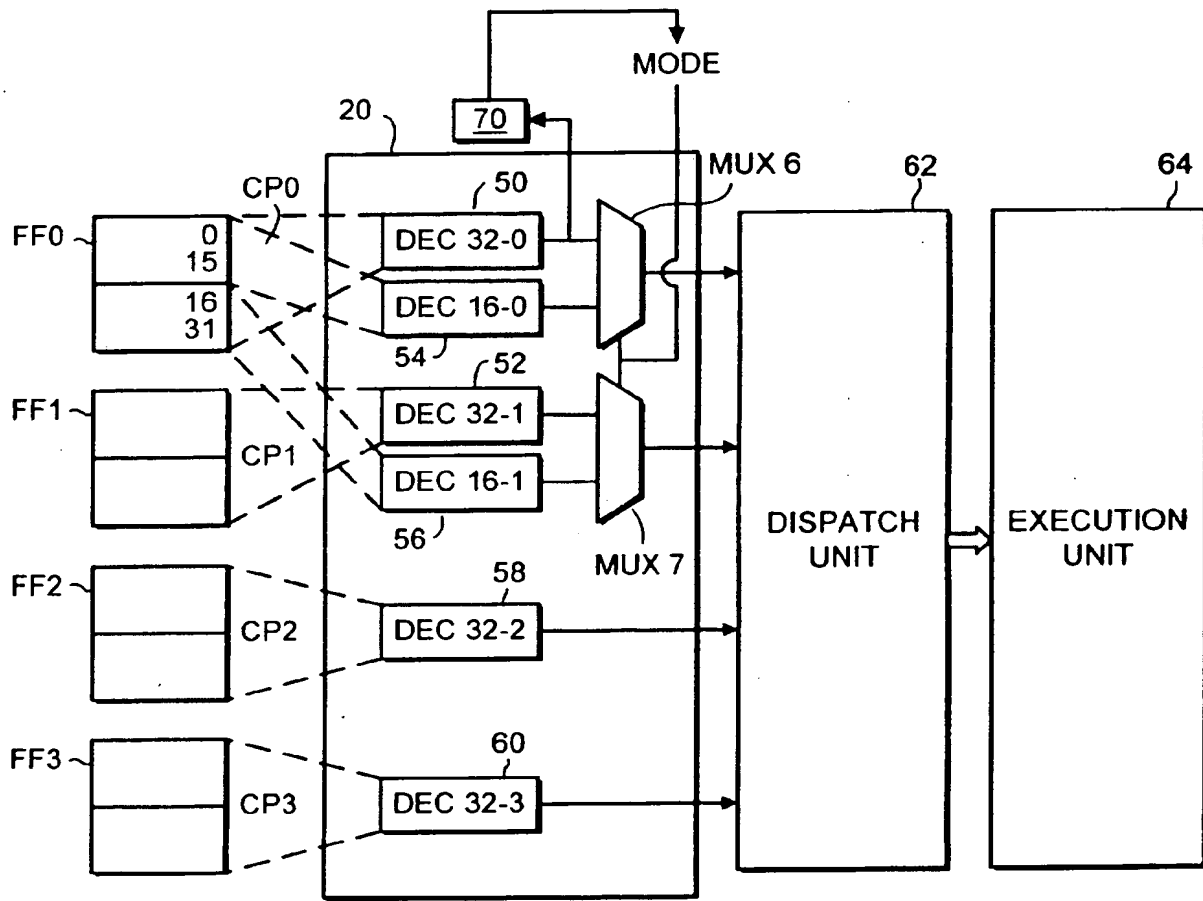


FIG. 5



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Application Number  
EP 99 41 0043

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